```cpp
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 Assignment: Deliverable 6
 purpose:    To contol a 4WD Car
 Class:      MakeCourse EEL4935.003S17
 Professor:  Rudy Schlaf
 Created by: Bello Abdulkareem
 DATE:       03/12/2017
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//constants won't change. They're used here to set pin numbers:
int LeftA = 5; // read the input on digital pin 5:
int LeftB = 6; // read the input on digital pin 6:
int rightA = 9;// read the input on digital pin 9:
int rightB = 10; // read the input on digital pin 10:
int acc = 255; // speed of the actuator:
int state = 'g'; // initial state 103

void setup()
{
  Serial.begin(9600);   // initialize serial communication at 9600 bits per second:
  pinMode(rightA, OUTPUT); // initialize the right A pin as an output
  pinMode(rightB, OUTPUT);// initialize the right B pin as an output
  pinMode(LeftA, OUTPUT); // initialize the left A pin as an output
  pinMode(LeftB, OUTPUT);// initialize the left A pin as an output
}

void loop()
{
  if (Serial.available() > 0)
  {
    state = Serial.read();
  }
  if (state == 'a') //
  {
    // To move/acclerate the 4WD Car Forward
    Serial.println(state);
    analogWrite(rightB, 0); //right rear wheel no movement
    analogWrite(LeftB, 0);  //left rear wheel no movememt
    analogWrite(rightA, acc);//right front wheel accelerate
    analogWrite(LeftA, acc); //left front wheel accelerate
  }
  if (state == 'b')
  {
    // To turn the 4WD Car left
    Serial.println(state);
    analogWrite(rightB, 0);//right rear wheel no movement
    analogWrite(LeftB, acc); //left rear wheel accelerate
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    analogWrite(LeftA, 0); //left rear front no movement
    analogWrite(rightA, acc); //right front wheel accelerate
  }
  if (state == 'c')
  { // To Stop the 4WD Car
    Serial.println(state);
    analogWrite(rightB, 0); //right rear wheel no movement
    analogWrite(LeftB, 0);//left rear wheel no movement
    analogWrite(rightA, 0);//right front wheel no movement
    analogWrite(LeftA, 0);//left front wheel no movement
  }
  if (state == 'd')
  {
    // To turn the 4WD Car right
    Serial.println(state);
    analogWrite(rightB, acc); //right rear wheel accelerate
    analogWrite(LeftB, 0);//left rear wheel no movement
    analogWrite(rightA, 0);//right front wheel no movement
    analogWrite(LeftA, acc);//left front wheel accelerate
  }
  if (state == 'e')
  {
    // To Reverse the 4WD Car
    Serial.println(state);
    analogWrite(rightA, 0);//right front wheel no movement
    analogWrite(LeftA, 0);//left front wheel no movement
    analogWrite(rightB, acc);//right rear wheel accelerate
    analogWrite(LeftB, acc);//left rear wheel accelerate
  }
}
```